

Identification code for ULTRACT – MINACT motors

UL **1** **0** **0** **7** . **F** **1** **0** **3** . **E** . **B** **I** **U**

<p>Identifying the size: stating the approximate height of the axis in cm</p> <p>Available sizes: 02 = 55mm sq. 04 = 85mm sq. 05 = 100mm sq. 07 = 145mm sq. 10 = 200mm sq. (224mm if ventilated) 13 = 264mm sq. (294mm if ventilated)</p>	<p>Identifying the torque: Stating the approximate value of the nominal torque</p>	<p>Identification field of servo-ventilated motors</p>	<p>Identifying the nominal speed: <u>rad/s</u> 10</p>	<p>Identifying the running voltage at the nominal speed: 1 = 110/125 Vac 2 = 220/240 Vac 3 = 380/440 Vac 4 = 24 Vac 5 = 48 Vac 6 = 460 Vac</p>	<p>Identifying the seek sensor: A = absent S = sincos 2048 i/rev + 1 cycle/revolution, differential output R = 2 poles resolver T = encoder 1024 i/rev F = encoder 2048 i/rev G = encoder 4096 i/rev H = Hall sensor M = singleturn absolute ENDAT encoder N = multiturn absolute ENDAT encoder</p>	<p>Sections available for additional specifications: K = shaft with key B = safety brake I = IP65 protection M = motor terminal board E = fitting for additional encoder C = standard military connectors Y = Interconnectron sign connector Z = Interconnectron power connector U = support feet (B3 version) W = KTY 84 linear thermal probe X = special version (pls. specify)</p>
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For instance, the identification code used will state:

Servomotor type **UL 10** (square200) **07** (\approx 70Nm) **F** (servoventilated) **10** (105 rad/s) **3** (380v) **E** (digital encoder 1024 i/rev) **B** (safety brake) **I** (IP65 protection) **U** (B3 version, with feet).